

A Reasonably Gradual Dependent Type Theory

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Prototyping with dependent types

```
Inductive vect (A : Type) :  $\mathbb{N}$   $\rightarrow$  Type :=  
| nil : vect A 0  
| _::_ {n :  $\mathbb{N}$ } (head : A) (tail : vect A n) : vect A (1+n)
```

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$\text{vect } A (1 + ?)$

$1 + ? \sim ?$

Prototyping with dependent types

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head: forall (A: Type) (n: ℕ), vect A (1+n) → A

head ℕ ? (filter even (1 :: 2 :: 4 :: nil))

head ℕ ? (filter even nil)

Equations filter {A : Type} (P : A → ℬ) {len : ℕ} (l : vect A len) : vect A ? :=
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$$\text{head } \mathbb{N} \text{ ? } (\text{filter even } (1 :: 2 :: 4 :: \text{nil})) \rightsquigarrow \text{head } \mathbb{N} \text{ ? } (2 :: 4 :: \text{nil})$$
$$\text{head } \mathbb{N} \text{ ? (filter even nil)} \rightsquigarrow \text{head } \mathbb{N} \text{ ? nil}$$

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Equations filter {A : Type} (P : A → ℬ) {len : ℕ} (l : vect A len) : vect A ? :=
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$$\text{head } \mathbb{N} \text{ ? (filter even nil)} \rightsquigarrow \text{head } \mathbb{N} \text{ ? nil} \rightsquigarrow \text{err}$$

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Equations filter {A : Type} (P : A → ℤ) {len : ℕ} (l : vect A len) : vect A ? :=
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$$1 + ? \sim ?$$

Prototyping with dependent types

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head: forall (A: Type) (n: ℕ), vect A (1+n) → A
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`head N ? (filter even nil)` $\rightsquigarrow$ `head N ? nil` $\rightsquigarrow$ `err`

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filter P (head :: tail) when not (P head) := filter tail
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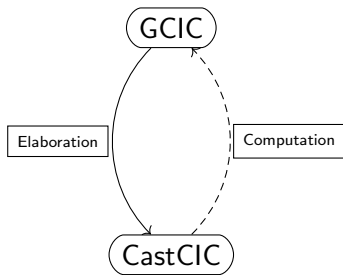
$$\text{filter } P \text{ (head :: tail)} := \underbrace{\text{head :: (filter tail)}}_{\text{vect } A \text{ (1+?)}} : \text{vect } A \text{ ?}$$

```
if l = nil
  then 0
  else ?
```

$$1 + ? \sim ?$$

GCIC & CastCIC: a marriage of Gradual & Dependent Types

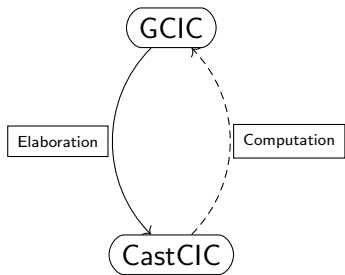
2



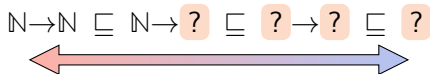
- ▷ Unknown terms and types $?_A : A$
- ▷ Errors $\text{err}_A : A$
- ▷ Casts $t : A \implies \langle B \Leftarrow A \rangle t : B$

GCIC & CastCIC: a marriage of Gradual & Dependent Types

2



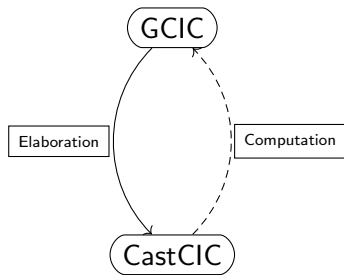
Precision between types



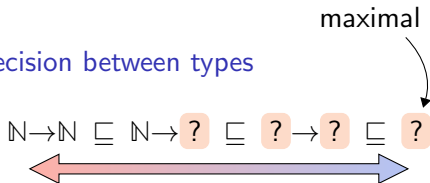
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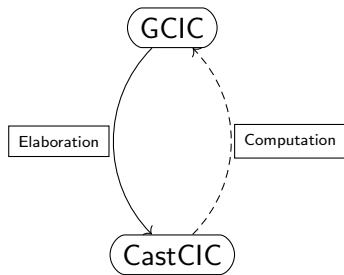
Precision between types



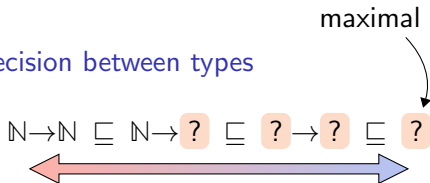
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GCIC & CastCIC: a marriage of Gradual & Dependent Types

2



Precision between types



Precision enforces cast validity:

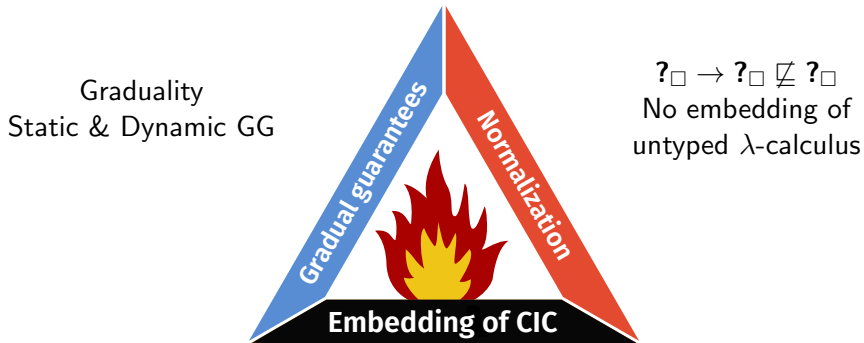
$$A \subseteq B \implies A \begin{matrix} \xrightarrow{\langle B \Leftarrow A \rangle} \\ \xleftarrow{\langle A \Leftarrow B \rangle} \end{matrix} B$$

Graduality [New & Ahmed 2018]

- ▶ Unknown terms and types $?_A : A$
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- ▶ Casts $t : A \implies \langle B \Leftarrow A \rangle t : B$

The Fire Triangle of Graduality

From Gradualizing the CIC [TOPLAS 2022]



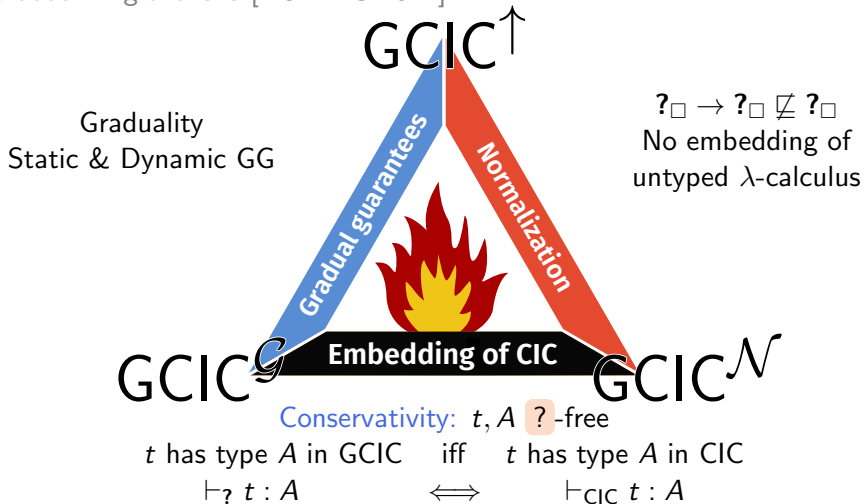
Conservativity: t, A λ -free

t has type A in GCIC iff t has type A in CIC

$\vdash_{\lambda} t : A$ $\iff$ $\vdash_{\text{CIC}} t : A$

The Fire Triangle of Graduality

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CastCIC ^{$\mathcal{N}$} : Normalizing, conservative over CIC, not gradual

How far is CastCIC ^{$\mathcal{N}$} from actually being gradual ?

Internal precision in GRIP

$\text{CastCIC}^{\mathcal{N}}$: Normalizing, conservative over CIC, **not gradual**

How far is $\text{CastCIC}^{\mathcal{N}}$ from actually being gradual ?

Make precision internal so that we can reason on it!

$$\text{GRIP} = \text{CastCIC}^{\mathcal{N}} + \sqsubseteq + \mathbb{P}$$

CastCIC^N: Normalizing, conservative over CIC, **not gradual**

$$\text{GRIP} = \text{CastCIC}^{\mathcal{N}} + \sqsubseteq + \mathbb{P}$$

$$\frac{\Gamma \vdash A, B : \square_i}{\Gamma \vdash A \sqsubseteq_i B : \mathbb{P}}$$

$$\frac{\Gamma \vdash A, B : \square_i \quad \Gamma \vdash a : A \quad \Gamma \vdash b : B}{\Gamma \vdash a \mathrel{_{A \sqsubseteq B}} b : \mathbb{P}}$$

$\mathbb{P}$: Pure universe of propositions

CastCIC^N: Normalizing, conservative over CIC, **not gradual**

$$\text{GRIP} = \text{CastCIC}^{\mathcal{N}} + \sqsubseteq + \mathbb{P}$$

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$\mathbb{P}$: Pure universe of propositions for **sound reasoning**

no error,
no casts,
no ?

definitionally
proof-irrelevant

Dynamic Gradual Guarantee

$$\text{DGG} : \forall (A : \square) (C : A \rightarrow \mathbb{B}) (x \ y : A), x \sqsubseteq_A y \rightarrow C \ x \sqsubseteq_{\mathbb{B}} C \ y.$$

$$\text{DGG } A \ C \text{ holds} \iff C \sqsubseteq_{A \rightarrow \mathbb{B}} C \iff C \text{ monotone wrt. } \sqsubseteq$$

Proofs of precision – External meaning

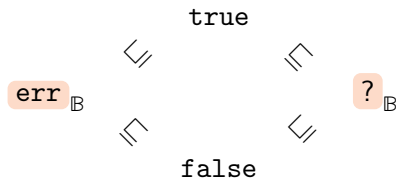
5

Dynamic Gradual Guarantee

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DGG correspond to [error-approximation](#):



$$\text{add1} : \mathbb{N} \rightarrow \mathbb{N} := \lambda x : \mathbb{N}. x + 1$$
$$\text{add?} : ?_{\square} \rightarrow \mathbb{N} := \lambda x : ?_{\square}. (\langle \mathbb{N} \Leftarrow ?_{\square} \rangle x) + 1$$
$$\text{add1} \mid_{\mathbb{N} \rightarrow \mathbb{N}} \sqsubseteq_{?_{\square} \rightarrow \mathbb{N}} \text{add?} \quad \Longrightarrow \quad \text{add? does not error on good input}$$

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$$\frac{\forall (x : \mathbb{N})(z : ?_{\square}), x \sqsubseteq_{\mathbb{N} \rightarrow ?_{\square}} z \rightarrow \text{add1 } x \sqsubseteq_{\mathbb{N}} \text{add? } z}{\text{add1}_{\mathbb{N} \rightarrow \mathbb{N}} \sqsubseteq_{?_{\square} \rightarrow \mathbb{N}} \text{add?}} \sqsubseteq \text{ on } \rightarrow$$

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$$\frac{\frac{x : \mathbb{N}, z : ?_{\square}, xz : x \sqsubseteq_{\mathbb{N} \rightarrow ?_{\square}} z \quad \vdash \quad x + 1 \sqsubseteq_{\mathbb{N}} (\langle \mathbb{N} \Leftarrow ?_{\square} \rangle z) + 1}{\forall (x : \mathbb{N})(z : ?_{\square}), x \sqsubseteq_{\mathbb{N} \rightarrow ?_{\square}} z \quad \rightarrow \quad \text{add1 } x \sqsubseteq_{\mathbb{N}} \text{add? } z}}{\text{add1 } \sqsubseteq_{\mathbb{N} \rightarrow \mathbb{N}} \text{add?}} \quad \begin{array}{l} \text{Intros, compute} \\ \sqsubseteq \text{ on } \rightarrow \end{array}$$

Proofs of precision – An example

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 \frac{}{x : \mathbb{N}, z : ?_{\square}, xz : x \sqsubseteq_{?_{\square}} z \vdash x \sqsubseteq_{\mathbb{N}} \langle \mathbb{N} \Leftarrow ?_{\square} \rangle z} \quad \langle \mathbb{N} \Leftarrow ?_{\square} \rangle \text{ right adjoint} \\
 \frac{}{x : \mathbb{N}, z : ?_{\square}, xz : x \sqsubseteq_{?_{\square}} z \vdash x + 1 \sqsubseteq_{\mathbb{N}} (\langle \mathbb{N} \Leftarrow ?_{\square} \rangle z) + 1} \quad +1 \text{ monotone} \\
 \frac{}{\forall (x : \mathbb{N})(z : ?_{\square}), x \sqsubseteq_{?_{\square}} z \rightarrow \text{add1 } x \sqsubseteq_{\mathbb{N}} \text{add? } z} \quad \text{Intros, compute} \\
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 \end{array}$$

Reasoning principles for $\sqsubseteq$

- ▷ heterogeneous transitivity

$$a \sqsubseteq_A b \wedge b \sqsubseteq_B c \rightarrow a \sqsubseteq_C c,$$

- ▷ quasi-reflexivity

$$a \sqsubseteq_A b \rightarrow a \sqsubseteq_A a \wedge b \sqsubseteq_B b,$$

- ▷ adjunction properties

$$A \sqsubseteq_i B \rightarrow \langle B \Leftarrow A \rangle a \sqsubseteq_B b \iff a \sqsubseteq_A b \iff a \sqsubseteq_A \langle A \Leftarrow B \rangle b,$$

- ▷ decomposition through upper bounds

$$A, B \sqsubseteq_i X \rightarrow a \sqsubseteq_A b \iff \langle X \Leftarrow A \rangle a \sqsubseteq_X \langle X \Leftarrow B \rangle b.$$

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However

$$\triangleright A \sqsubseteq_{\square_i} B \iff A \sqsubseteq_i B \wedge B \sqsubseteq_i ?_{\square_i}$$

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However

- ▷ $A \sqsubseteq_{\square_i} B \iff A \sqsubseteq_i B \wedge B \sqsubseteq_i ?_{\square_i}$
- ▷ $?_{\square_i} \rightarrow ?_{\square_i} \not\sqsubseteq_i ?_{\square_i}$
- ▷ $?_{\square_i}$ maximal for $\sqsubseteq_{\square_i}$, not for $\sqsubseteq_i$

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$$\triangleright ?_{\square_i} \text{ maximal for } \sqsubseteq_{\square_i}, \text{ not for } \sqsubseteq_i$$

- ▷ Mitigated by explicit cumulativity

$$\iota(?_{\square_i} \rightarrow ?_{\square_i}) \sqsubseteq_{i+1} ?_{\square_{i+1}}$$

How good is GRIP? Metatheory!

Consistency $\not\vdash_{\text{GRIP}} t : \perp$ (where $\perp : \mathbb{P}$)

Idea: Build a model of GRIP in MLTT+SProp using partial pre-orders.
 $\llbracket \perp \rrbracket$ is empty in the model.

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Gradual fragment GRIP[↑] Automatically precise terms

Idea: Raise universe levels on Π

$$\frac{\Gamma \vdash_{\text{GRIP}^\uparrow} A : \square_i \quad \Gamma, x : A \vdash_{\text{GRIP}^\uparrow} B : \square_i}{\Gamma \vdash_{\text{GRIP}^\uparrow} \Pi x : A. B : \square_{i+1}}$$

Summary & Future work

GRIP = Partially gradual type theory + internal precision

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- ▷ Model in Coq based on partial pre-orders

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- ▷ Addresses DGG in an exceptional world (see paper).

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- ▷ Proof of concept for GRIP in Agda
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- ▷ Addresses DGG in an exceptional world (see paper).
- ▷ Internal reasoning to establish graduality post-hoc

GRIP = Partially gradual type theory + internal precision

- ▷ Proof of concept for GRIP in Agda
- ▷ Model in Coq based on partial pre-orders
- ▷ Non gradual operations, e.g. catch of `?`/`err` on inductives
- ▷ Addresses DGG in an exceptional world (see paper).
- ▷ Internal reasoning to establish graduality post-hoc

GRIP is a type theory, not yet a proof assistant:

- ▷ Elaboration from a gradual source
- ▷ General inductive types
- ▷ An actual implementation?

Thank You!

Equations `argOfDescr (s : stringDescr) : Type :=`
 `argOfDescr "" := unit ;`
 `argOfDescr ("%d" @ rest) :=  $\mathbb{N} \rightarrow$  argOfDescr rest;`
 ...

Definition `printf : forall (s : stringDescr), argOfDescr s := ...`

- ▷ `printf` does not type in $\text{GRIP}^\uparrow$ (arbitrary arity)
- ▷ `printf` does type in `GRIP`
- ▷ It is **not** self-precise
- ▷ but its retrictions to `stringDescr` bounded by some fixed length **are self-precise**.